



## 3D ABAQUS SIMULATION OF BENT SOFTWOOD ELEMENTS

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The article presents research on modelling fracture in softwood bent elements. This kind of timber is the one most exploited for construction. Authors present a brief review on the subject with emphasis on three basic attempts: Linear Elastic Fracture Mechanics (LEFM), Continuum Damage Mechanics (CDM) and Hill's Function (HF). Proposed 3D solution bases on Hill's Function applied in the ABAQUS FEM code. The new idea includes isolating theoretical compression and tension zones in a model. Then, it is possible to distinguish between compressive and tensile strength and predict a real behaviour of bent elements. Introducing general dependencies between material properties leads to the need of determining only longitudinal elastic modulus ( $E_L$ ) and modulus of rupture (MOR). It is practical because these parameters are the main reported in a scientific and technical literature. Authors describe all of the assumptions in details. The experimental tests and Digital Image Correlation method (DIC) validate the FEM model.

**Keywords:** FEM, Wood Modelling, Softwood, Fracture, Destruction

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## 1. INTRODUCTION

Literature describes a nonlinear behaviour of timber with three main concepts. The first is the LEFM (Linear Elastic Fracture Mechanics). Basic material properties regulating the fracture process are critical stress intensity factor (fracture toughness) and energy release rate in corresponding modes (Fig. 1).

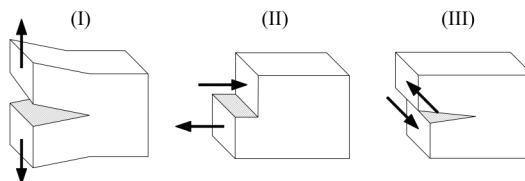


Fig. 1. Basic modes of fracture.

Silva [1] and Kossakowski [2, 3] carry out numerical analyses of DCB (Double Cantilever Beam) and ENF (End Notched Flexure) test (Fig. 2). They calculate energy release rate in mode I and II ( $G_{Ic}$  and  $G_{IIc}$ ) for pinewood. Experimental determination of fracture toughness and energy release rate in timber is also a subject of other finds, for example done by Prokopski [4] or Yoshikara [5].

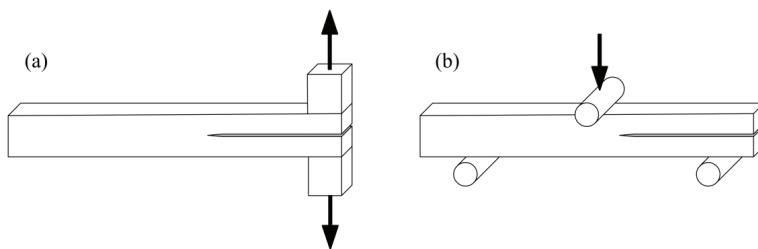


Fig. 2. (a) DCB – Double Cantilever Beam, (b) ENF – End Notched Flexure.

Stanzl-Tschegg [6] and Vasic [7] propose a WS (Wedge-Splitting) sample for testing a fracture in mode I (Fig. 3a). The value of  $G_{Ic}$  they measure is comparable to this presented by Kossakowski [3]. Fortino [8] adds cohesive elements to the WS sample on the expected crack path. He gets a good agreement with Stanzl-Tschegg [6] experimental results.

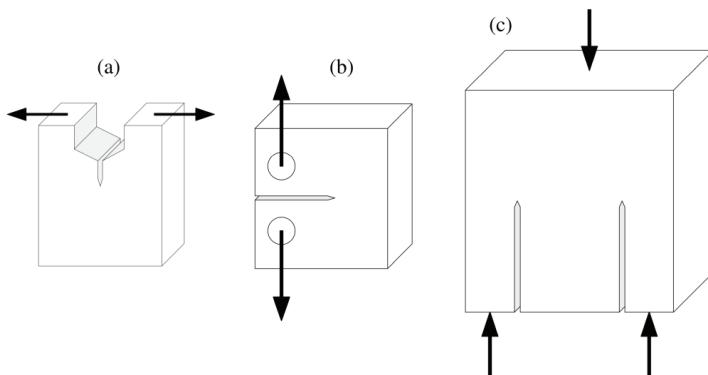


Fig. 3. (a) WS – Wedge Splitting sample, (b)  $K_{Ic}$  specimen, (c)  $K_{IIc}$  specimen.

Qiu [9, 10] presents a different concept. He calculates the fracture toughness  $K_{Ic}$  and  $K_{IIc}$  from the standard specimens (Fig. 3 b,c). Then, creates FEM model using XFEM (Extended Finite Element) method, which gives results close to laboratory tests.

The second modelling approach is CDM (Continuum Damage Mechanics). Constitutive law is bilinear and includes softening. It makes possible to distinguish material properties in different directions and depending on a stress state (compression, tension). Sandhaas [11] proposes a 3D model, in which he takes into account plastic behaviour in compression and brittle in tension. Nine different material degradation parameters control a fracture development. Their calculation bases on the introduced fracture energy in a respective direction. Orlando [12] uses the Sandhaas' model to predict a damage process in wooden girders cut in selected places and repaired with glued rods. Khorsandnia [13] and Valipour [14] propose a 2D model based on Hashin's criterion. It provides a bilinear material characteristic with a distinction between compression and tension. The authors examine full and I-beam girders with holes or cuts and get consistency of results.

The third concept is HF (Hill's Function), representing an anisotropic plastic flow after reaching a yield point. General advantages and disadvantages of using the criterion describe Mascia and Simoni [15]. Oudjene and Khelifa [16, 17] consider a compression of cuboidal samples parallel to grains and validate the FEM model based on Reiterer and Stanzl-Tschegg experiments [18]. Later, they expand it to the sample with a circular hole and steel dowel (Fig. 4a). Simulations cause timber to crush in a contact zone. Pranata [19] and Santos [20] build a 3D model and change the orientation of fibres. This time, grains of adjacent elements are perpendicular to each other. Because of the arrangement the dowel presses the components both along and across the fibres

(Fig. 4b). This is a more complex situation than in the case of preceding study. To predict a crack, the authors add a cohesive surface on the expected fracture path.

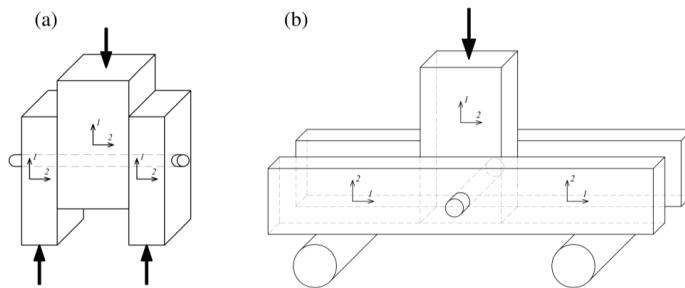


Fig. 4. (a) Oudjene specimen, (b) Santos specimen.

Summarising, a 3D solution for modelling wood, which incorporates sufficient complexity is Hill's Function. The advantages are a fast convergence of computations and simple implementation of required parameters. Despite this, the model needs a general enrichment to well represent stress state in bending. The authors present the assumptions in the following part of the article.

## 2. DESCRIPTION OF THE MODEL

Wood is an orthotropic material. Constitutive relation determining a linear-elastic behaviour in a 3D space is:

$$(2.1) \quad \begin{bmatrix} \varepsilon_{11} \\ \varepsilon_{22} \\ \varepsilon_{33} \\ \gamma_{12} \\ \gamma_{13} \\ \gamma_{23} \end{bmatrix} = \begin{bmatrix} \frac{1}{E_1} & -\frac{\nu_{21}}{E_2} & -\frac{\nu_{31}}{E_3} & 0 & 0 & 0 \\ -\frac{\nu_{12}}{E_1} & \frac{1}{E_2} & -\frac{\nu_{32}}{E_3} & 0 & 0 & 0 \\ -\frac{\nu_{13}}{E_1} & -\frac{\nu_{23}}{E_2} & \frac{1}{E_3} & 0 & 0 & 0 \\ 0 & 0 & 0 & \frac{1}{G_{12}} & 0 & 0 \\ 0 & 0 & 0 & 0 & \frac{1}{G_{13}} & 0 \\ 0 & 0 & 0 & 0 & 0 & \frac{1}{G_{23}} \end{bmatrix} \begin{bmatrix} \sigma_{11} \\ \sigma_{22} \\ \sigma_{33} \\ \tau_{12} \\ \tau_{13} \\ \tau_{23} \end{bmatrix}$$

ABAQUS FEM code [21] allows applying the Hill's function to represent an anisotropic plastic flow of a material after reaching a yield point. The function is:

$$(2.2) \quad f(\sigma) = \sqrt{F(\sigma_{22} - \sigma_{33})^2 + G(\sigma_{33} - \sigma_{11})^2 + H(\sigma_{11} - \sigma_{22})^2 + 2L\tau_{23}^2 + 2M\tau_{31}^2 + 2N\tau_{12}^2}$$

where:

$$(2.3) \quad F = \frac{1}{2} \left( \frac{1}{R_{22}^2} + \frac{1}{R_{33}^2} - \frac{1}{R_{11}^2} \right) \quad G = \frac{1}{2} \left( \frac{1}{R_{33}^2} + \frac{1}{R_{11}^2} - \frac{1}{R_{22}^2} \right)$$

$$(2.5) \quad H = \frac{1}{2} \left( \frac{1}{R_{11}^2} + \frac{1}{R_{22}^2} - \frac{1}{R_{33}^2} \right) \quad L = \frac{3}{2R_{23}^2} \quad M = \frac{3}{2R_{13}^2} \quad N = \frac{3}{2R_{12}^2}$$

Because Hill's Function does not distinguish between compressive and tensile strength, we propose a theoretical separation of compression and tension zones (Fig. 5).

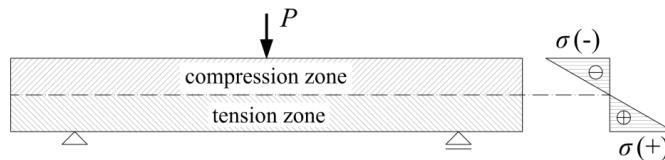


Fig. 5. Theoretical isolation of the compression and tension zones.

After making this assumption, the constitutive law is (Fig. 6):

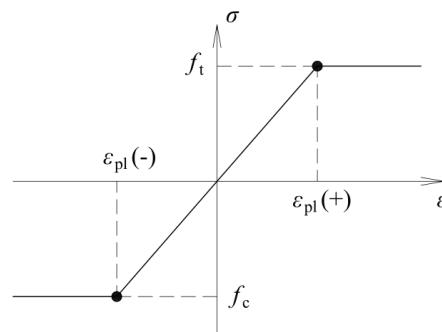


Fig. 6. Constitutive law for wood used in the model.

### 3. LABORATORY TESTS AND NUMERICAL SIMULATIONS

The initial step is preparing 10 specimens of pinewood with dimensions of  $19 \times 45 \times 500$  mm. All are cut from the same batch of softwood, dried to 16-18% of moisture content. Knots and other defects are neglected to get as homogenous timber structure as possible. During preparation and testing the samples, a relative air humidity is on the level of 60%. Fig. 7 shows a simplified pattern for defining axes for a 3D orthotropic model. In the illustration there is also visible a typical sample with two surfaces painted with a special gradient. In the front and bottom surface it is possible to examine the method of destruction compared to the FEM model. The testing machine is MTS 809. An additional equipment used for measurements is the ARAMIS system, based on Digital Image Correlation (DIC).

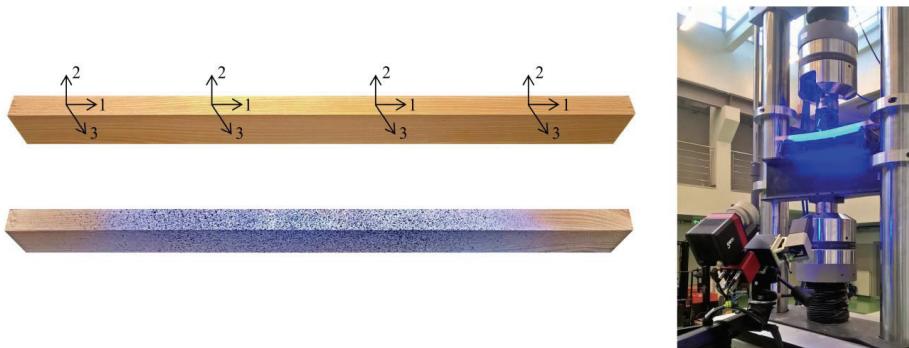


Fig. 7. A typical sample and the laboratory setup.

Because wood is a material tested all over the world, a procedure of selection of the parameters for modelling should include using properties from the literature. The example of such a position may be Wood Handbook [22]. Modulus of elasticity along the fibres is determined based on measuring the deflection of the bottom of the beam. Even in the orthotropic model, the longitudinal modulus of elasticity has the biggest impact on deflection.

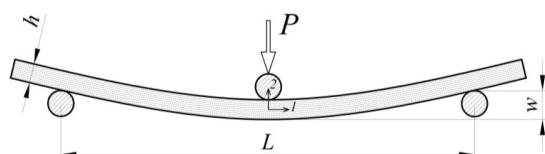


Fig. 8. Denotations for a three point bending test.

The value of the displacement of the middle point of the beam in a three point bending (Fig. 8) determines the formula:

$$(3.1) \quad w = \frac{PL^3}{48E_l J} + \frac{PL}{4G_{12} A'}$$

where:

$$A' = \frac{5}{6}bh \text{ - modified rectangular cross-sectional area}$$

$$G_{12} = \frac{E_1}{16} \text{ - shear modulus depending on the longitudinal modulus}$$

$$J = \frac{bh^3}{12} \text{ - moment of inertia of the rectangular section}$$

After substituting all the variables, we get an equation that allows calculating the deflection value depending only on the longitudinal modulus of elasticity. From laboratory tests it is feasible to get  $P/w$  rate in the linear-elastic range, and thus the values of the longitudinal modulus of elasticity:

$$(3.2) \quad E_l = \frac{P}{w} \left( \frac{L^3}{4bh^3} + \frac{24L}{5bh} \right)$$

Aramis system measures deflection ( $w$ ) at the bottom of the beam, while MTS machine records the applied force ( $P$ ). Calculation of other elastic parameters relates to Wood Handbook [22] and Kossakowski [2, 3]. In the both sources relations between elastic parameters are similar:

$$(3.3) \quad E_1 : E_2 : E_3 = 25 : 1.6 : 1$$

$$(3.4) \quad G_{12} : G_{13} : G_{23} = 10.4 : 7.7 : 1$$

Poisson's coefficients base on average values and are equal:  $\nu_{12}=0.335$ ,  $\nu_{13}=0.358$ ,  $\nu_{23}=0.416$ . Another parameter specified in the literature is tensile strength in bending, often called the modulus of rupture (MOR), calculated according to a simple formula from the theory of elasticity:

$$(3.5) \quad f_{t,1} = \frac{3}{2} \frac{P_{\max} L}{bh^2}$$

The authors point out that the remaining strengths depend on the tensile strength along the fibres. Based on the parameters marked in Wood Handbook [22], the dependencies are forming as the trend lines show (Fig. 9):

$$(3.6) \quad f_{c,1} = 0.513 \cdot f_{t,1} + 3.480$$

$$(3.7) \quad f_{c,2} = 0.075 \cdot f_{t,1} - 0.865$$

$$(3.8) \quad f_{v,12} = 0.083 \cdot f_{t,1} + 2.272$$

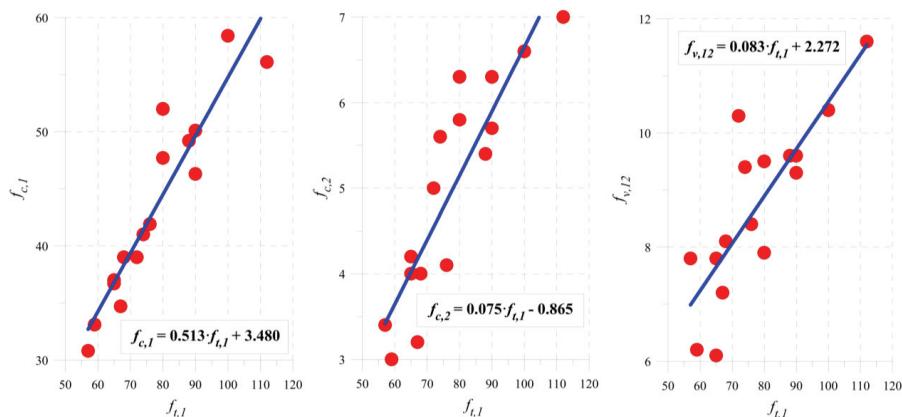


Fig. 9. Trend lines of the strengths determined based on laboratory tests.

Table 1. Elastic parameters and strengths of the tested softwood.

| Sample number | $E_1$ [GPa]   | $E_2$ [GPa]  | $E_3$ [GPa]  | $G_{12}$ [GPa] | $G_{13}$ [GPa] | $G_{23}$ [GPa] | $f_{t,1}$ [MPa] | $f_{c,1}$ [MPa] | $f_{c,2}$ [MPa] | $f_{v,12}$ [MPa] |
|---------------|---------------|--------------|--------------|----------------|----------------|----------------|-----------------|-----------------|-----------------|------------------|
| 1             | 11.574        | 0.741        | 0.463        | 0.723          | 0.536          | 0.070          | 92.91           | 51.05           | 6.10            | 9.89             |
| 2             | 15.955        | 1.021        | 0.638        | 0.997          | 0.738          | 0.096          | 109.29          | 59.44           | 7.33            | 11.23            |
| 3             | 15.089        | 0.966        | 0.604        | 0.943          | 0.698          | 0.091          | 88.41           | 48.74           | 5.77            | 9.52             |
| 4             | 15.576        | 0.997        | 0.623        | 0.974          | 0.721          | 0.094          | 91.83           | 50.50           | 6.02            | 9.80             |
| 5             | 15.738        | 1.007        | 0.630        | 0.984          | 0.728          | 0.095          | 92.5            | 50.84           | 6.07            | 9.86             |
| 6             | 16.874        | 1.080        | 0.675        | 1.055          | 0.781          | 0.101          | 101.74          | 55.57           | 6.77            | 10.61            |
| 7             | 15.955        | 1.021        | 0.638        | 0.997          | 0.738          | 0.096          | 100.42          | 54.89           | 6.67            | 10.51            |
| 8             | 17.199        | 1.101        | 0.688        | 1.075          | 0.796          | 0.103          | 103.77          | 56.61           | 6.92            | 10.78            |
| 9             | 14.873        | 0.952        | 0.595        | 0.930          | 0.688          | 0.089          | 94.81           | 52.02           | 6.25            | 10.05            |
| 10            | 13.413        | 0.858        | 0.537        | 0.838          | 0.621          | 0.081          | 82.69           | 45.82           | 5.34            | 9.05             |
| AVG           | <b>15.225</b> | <b>0.974</b> | <b>0.609</b> | <b>0.952</b>   | <b>0.705</b>   | <b>0.091</b>   | <b>95.84</b>    | <b>52.55</b>    | <b>6.32</b>     | <b>10.13</b>     |

Elastic parameters and strengths summarises Table 1. Because the proposed model does not distinguish between compressive and tensile strength and they are close to each other, we assume that  $f_{t,2} = f_{c,2}$ . In addition, parameters for axis (2) and (3) are equal  $f_{c,2} = f_{c,3}$  and shear strength

is identical in each direction  $f_{v,12} = f_{v,13} = f_{v,23}$ . In the next step, we calculate the parameters required in the dependencies 2.2-2.6 of Hill's Function. The reference value for all of them is the bending tensile strength  $f_{t,1}$ .  $R_{11}(+)$  means the coefficient used in the tension, while  $R_{11}(-)$  in the compression zone. Parameter  $\lambda$  calibrates the strength in the tension region. We use the formulas:

$$(3.9) \quad R_{11}(+) = \frac{\lambda f_{t,1}}{f_{t,1}} \quad R_{11}(-) = \frac{f_{c,1}}{f_{t,1}} = 0.548 \quad R_{22} = R_{33} = \frac{f_{c,2}}{f_{t,1}} = 0.066$$

$$(3.10) \quad R_{12} = R_{13} = R_{23} = \frac{\sqrt{3} f_{v,12}}{f_{t,1}} = 0.183$$

The 6<sup>th</sup> polynomial represents each of the experimental force-deflection curve ( $P/w$ ). This statistical approximation enables to mark the same points on a diagram, as calculated in the FEM model. Fig. 11a presents results from testing machine, average ultimate force and its average deviation. However, Fig. 11b shows the experimental average curve and a deviation envelope according to the 6<sup>th</sup> polynomial representation.

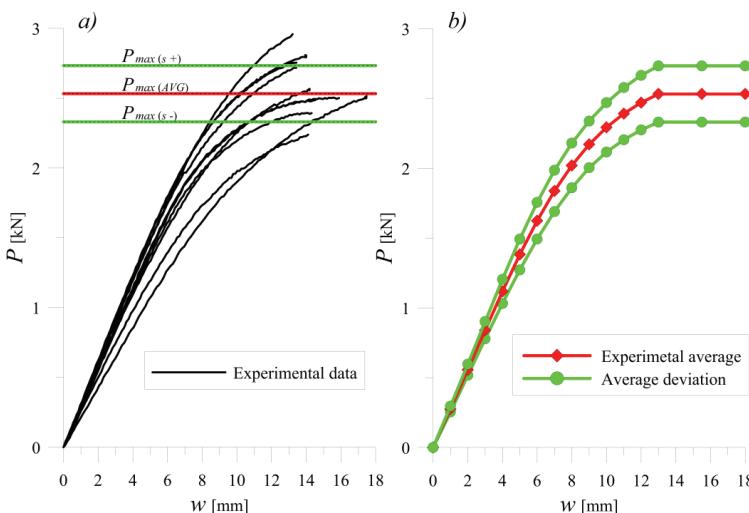


Fig. 10. Experimental  $P/w$  curves and its statistical approximations

In a numerical modelling, it is crucial to choose finite elements which behave well in a complex stress state. Hemanth [23] studies all the 3D elements, which are available in the ABAQUS FEM

code. He concludes that the finest are 20-node elements with 27 integration points, named C3D20. They are numerically expensive, but produce physical results in bending and stress concentration areas. The amount of four C3D20 members at the height of the bent sample gives results identical to the analytical solutions. Fig. 11 shows the finite element mesh and boundary conditions:

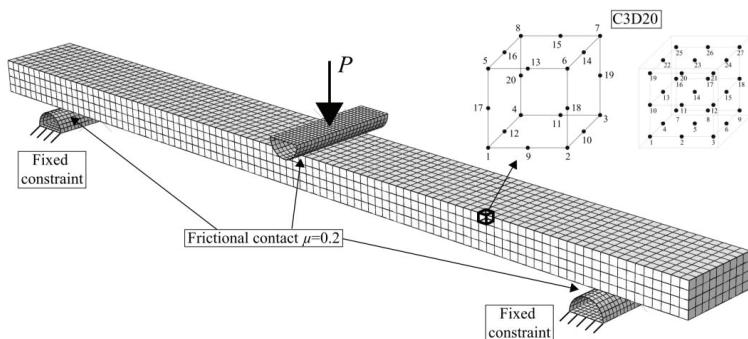


Fig. 11. Finite element mesh and boundary conditions used in the analyses.

Based on the investigations, we claim that the model reflects the stiffness of the real system in the linear-elastic range ( $K_u$ ). For the FEM model it is  $K_u = 0.285 \text{ kN/mm}$  and for the real samples  $K_u = 0.282 \text{ kN/m}$ . It approves the correctness of the selected parameters for an elastic modelling.

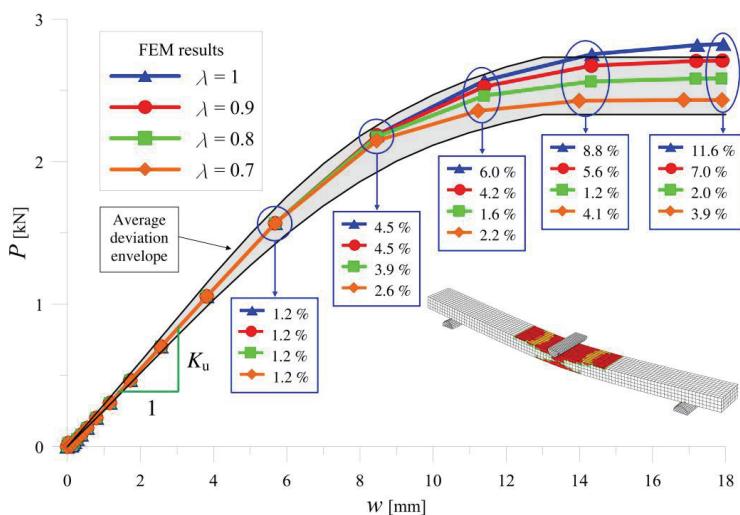


Fig. 12. Comparison of  $P/w$  relation from FEM model and laboratory tests.

However, we should calibrate the material in the FEM model to get the maximum force from laboratory experiments. For this purpose, we introduce the parameter  $\lambda$  changing tensile strength in the tension zone (formula 3.9). Calculations continue until the entire cross-section plasticises. The results of the maximum force got for most of the values are within the standard deviation of laboratory tests. A graph in Fig. 12 shows the numerical simulations related to laboratory tests. Frames in the marked points collect average errors for each value of  $\lambda$ . The most-matched results gives  $\lambda=0.8$ .

Therefore, we analyse the behaviour of the wooden beam in the non-elastic range and compare to the way of destruction achieved in experiments. Fig. 13 shows a comparison of plasticised zones from the FEM model (red) with zones of experimental gradient destruction because of stretching (yellow). We can notice that cracking of the wood in the tension zone does not occur in one point in the middle of the sample, but spread over a larger area. The proposed numerical model captures this behaviour well.

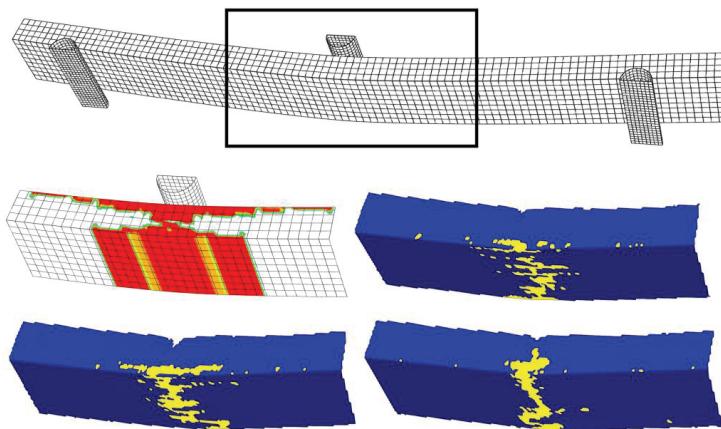


Fig. 13. Comparison of forms of destruction from the FEM model and laboratory tests.

#### 4. CONCLUSIONS

In summary, numerical modelling of wood is a complex process. There are no models in the literature regarding progressive damage that allow analysis of any kind of structure. Researchers calibrate each model depending on the expected stress state and the way of destruction.

The authors plan to use the model to predict a behaviour of wood-based composite bent girders, where, for example, a delamination of several bonded surfaces occurs as simultaneous. It leads to the desire of a solution for wood which is stable and incorporates a sufficient complexity. Amount of parameters and problems with convergence of the calculations in Hill's Function are much smaller than in case of other methods found in the literature. It is worth to point out the very practical aspect, as direct availability of the material model in ABAQUS FEM code.

The method presented in the paper enables modelling wood elements in a 3D state when bending. Theoretical isolation of the compression and tension zones enrich the solution. It allows to distinguish between different strengths of wood in each stress state. The FEM model represents both plastic flow in a middle stage of compression and maximum force prediction because of tension. Force-deflection response is comparable to a physical behaviour of the elements.

Considering all the above, we can state that we may use the model in a further research, after a proper calibration.

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Fig. 11. Finite element mesh and boundary conditions used in the analyses.

Rys. 11. Siatka elementów skończonych i warunki brzegowe wykorzystane w analizie.

Fig. 12. Comparison of  $P/w$  relation from FEM model and laboratory tests.

Rys. 12. Porównanie zależności  $P/w$  z modelem MES i badań laboratoryjnych

Fig. 13. Comparison of forms of destruction from the FEM model and laboratory tests.

Rys. 13. Porównanie form zniszczenia z modelem MES i badań laboratoryjnych.

Table 1. Elastic parameters and strengths of the tested softwood.

Tabela 1. Parametry sprężyste i wytrzymałości badanego drewna.

## SYMULACJA 3D ZGINANYCH ELEMENTÓW Z MIĘKKIEGO DREWNA W PROGRAMIE ABAQUS

*Słowa kluczowe:* MES, Modelowanie Drewna, Miękkie Drewno, Pękanie, Zniszczenie

### STRESZCZENIE:

Artykuł przedstawia sposób modelowania elementów zginanych wykonanych z miękkiego drewna. Taki rodzaj drewna jest najczęściej wykorzystywany w konstrukcjach budowlanych. Autorzy wykonali zwięzły przegląd sposobów modelowania drewna na podstawie literatury. Znają się w nim trzy podstawowe podejścia: liniowo-sprężysta mechanika pękania (LEFM), mechanika zniszczenia ośrodków ciągłych (CDM) i funkcja Hilla (HF). W pracy zaproponowano rozwiązanie oparte na funkcji Hilla, która dostępna jest w programie ABAQUS. Zróżnicowane zachowanie materiału przy ściskaniu i rozciąganiu osiągnięto poprzez teoretyczny podział modelu na strefę ściskaną

i rozciągana. W obu strefach przyjęto różną wytrzymałość wzdłuż włókien w zależności od panującego stanu naprężenia. Na podstawie badań laboratoryjnych wprowadzono ogólne zależności pomiędzy parametrami sprężystymi i wytrzymałościowymi. Dzięki temu do zastosowania modelu wystarczające jest obliczenie modulu sprężystości wzdłuż włókien ( $E_L$ ) i wytrzymałości na rozciąganie przy zginaniu (MOR). Oba parametry można wyznaczyć bezpośrednio w badaniu trójpunktowego zginania. Prawidłowość modelu MES została potwierdzona badaniami laboratoryjnymi oraz metodą cyfrowej korelacji obrazu (DIC). Model umożliwia przewidywanie zachowania elementów z drewna przy zginaniu w stanie 3D. Uwzględnia zarówno plastyczne płynięcie w środkowej fazie obciążenia, spowodowane przekroczeniem wytrzymałości na ścislanie, jak i przewidywanie siły maksymalnej w wyniku rozciągania. Rozwiążanie jest bardzo praktyczne ze względu na brak problemów ze zbieżnością obliczeń. Dodatkowo liczba wymaganych parametrów jest znacznie mniejsza niż w przypadku innych metod odnalezionych w literaturze.

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